

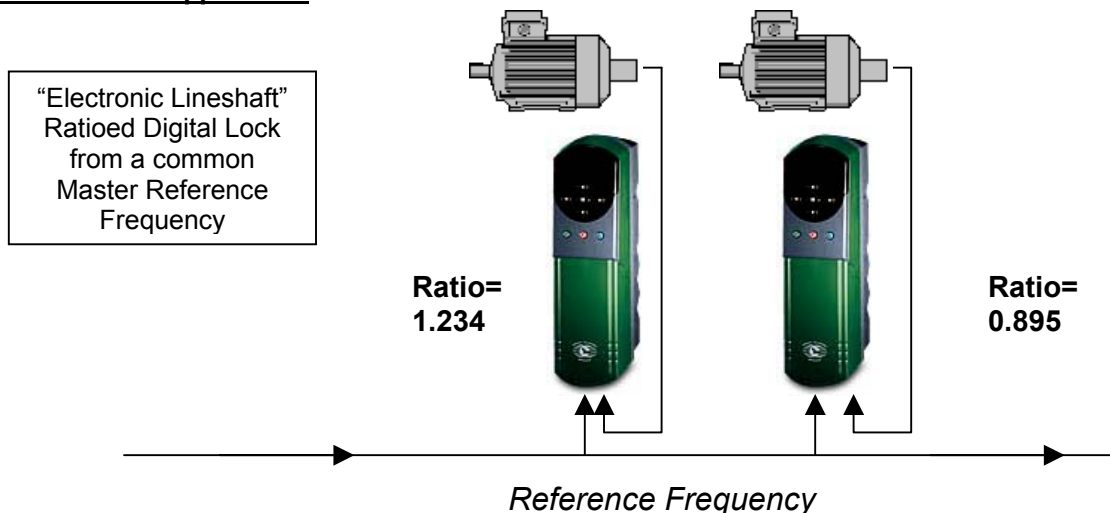
This Application Note is pertinent to the Unidrive Family

## Digital Locking Basics

The UD51 Second Encoder module provides the Unidrive with the ability to monitor speed and/or position of an additional encoder. Typically this module would be used to enable the Unidrive ( operating in the closed loop Vector or Servo modes ) to follow an external frequency in Digital Lock with ratio adjustability. This application note will provide some basic information to get started with a Digital Lock application.

### Typical Applications

#### Parallel Ratio Application



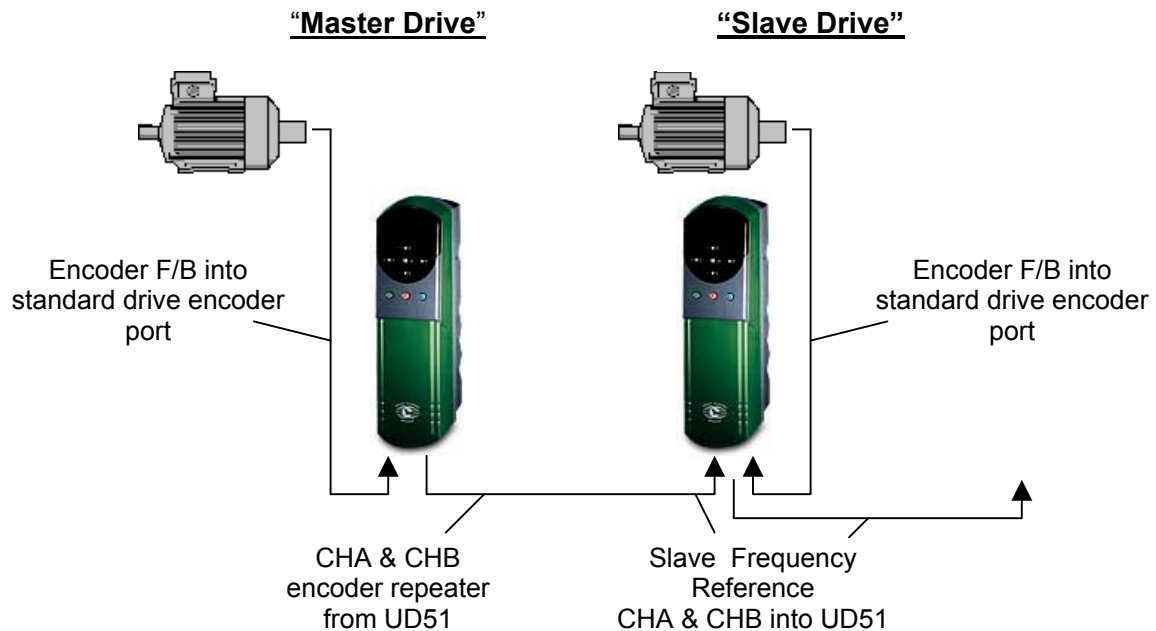
The reference frequency could be a simple differential frequency ( or frequency and direction) or a reference frequency from a quadrature source. In the example above, the master reference frequency would be repeated out of the 1<sup>st</sup> UD51 to the input of the next so that the reference source would experience only a single load.

The above application would be a "parallel" ratio control scheme where each drive is ratioed to a master line speed reference and would follow this line speed at its designated ratio but each drive ratio would be independent of each other.

For more information on the UD51 module, click on the link below:

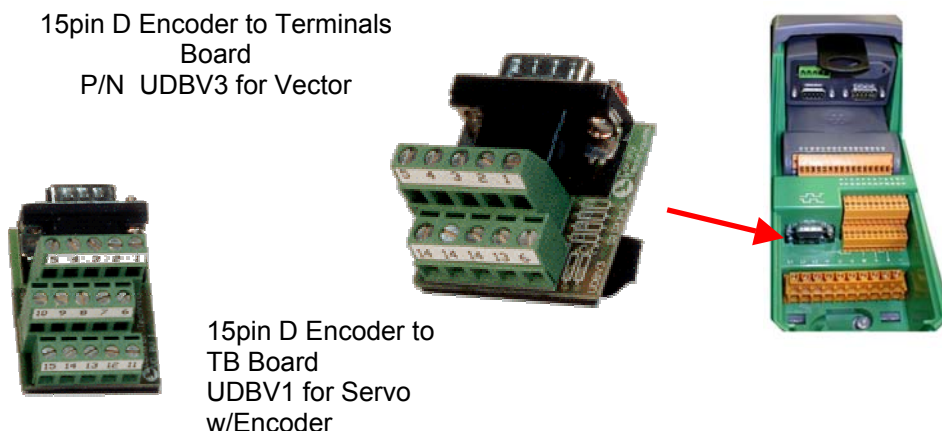
[www.emersonct.com/pdProducts/downloads/literaturePDF/pdCatalog2003/Unidrive.pdf](http://www.emersonct.com/pdProducts/downloads/literaturePDF/pdCatalog2003/Unidrive.pdf)

## Master/Slave “Cascaded Ratio” Situations

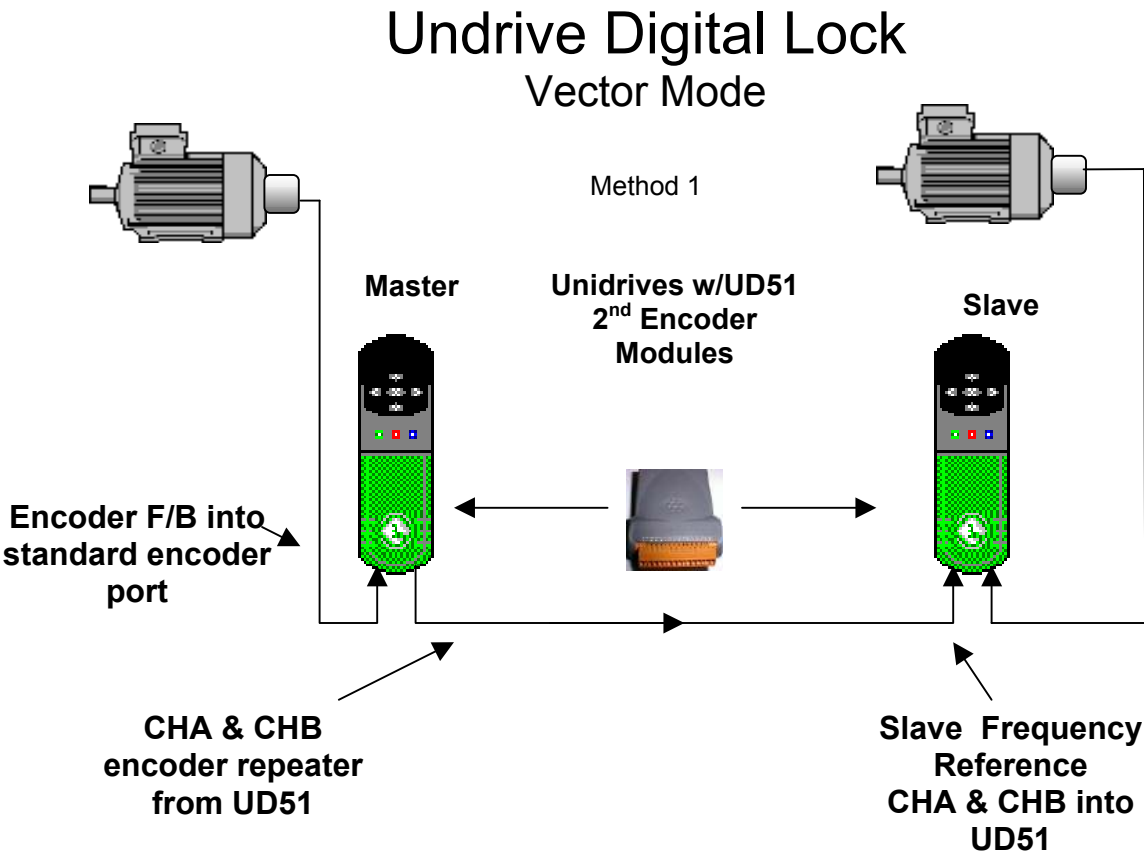


In this example, the source could be from another machine section that has an encoder as is desired to be followed such as a Master and Slave situation. The speed of other drives further downstream are dependent upon the ratios of drives before it in the cascaded ratio control method. The Master drive is using a UD51 to repeat the motor encoder quadrature signals. The Slave drive has a UD51 to receive the quadrature input. If desired, the slave can follow the master 1:1 or at some ratio (between 0.001-4.000) that can be controlled by the machine Operator.

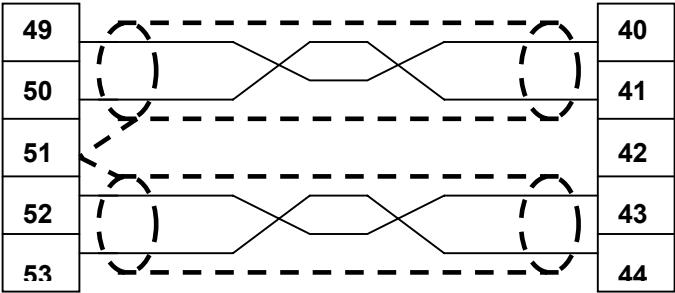
**Note:** To facilitate wiring of the reference frequency into the Unidrive on-board encoder feedback or reference input 15-pin D connector, an adapter board is available as shown below that so that soldering is not necessary.



Listed below are a few notes concerning conceptual hook-up and initial setup of the Unidrive performing Digital Lock operating in the a closed loop mode with encoder feedback.



# UD51



Individually shielded twisted pair cable with an over-all shield Belden 8777 or equiv

Available from Control Techniques Service Center

– call 716-774-0093 ask for Tech Support

# Undrive Digital Lock

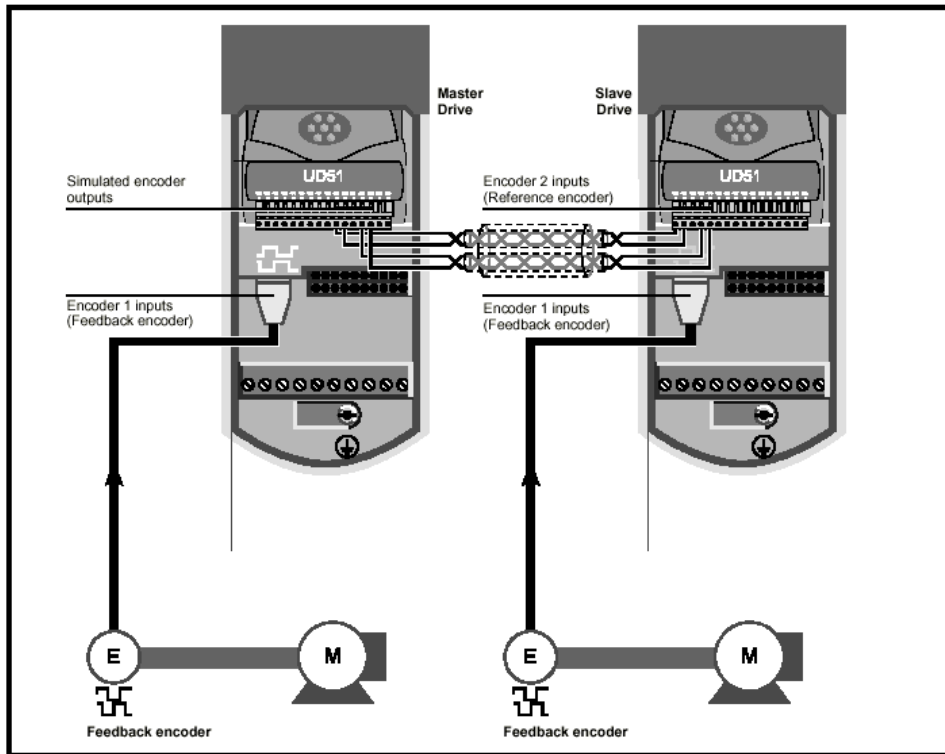


Figure 3-22 Master-slave signal connections for digital lock when encoders are used

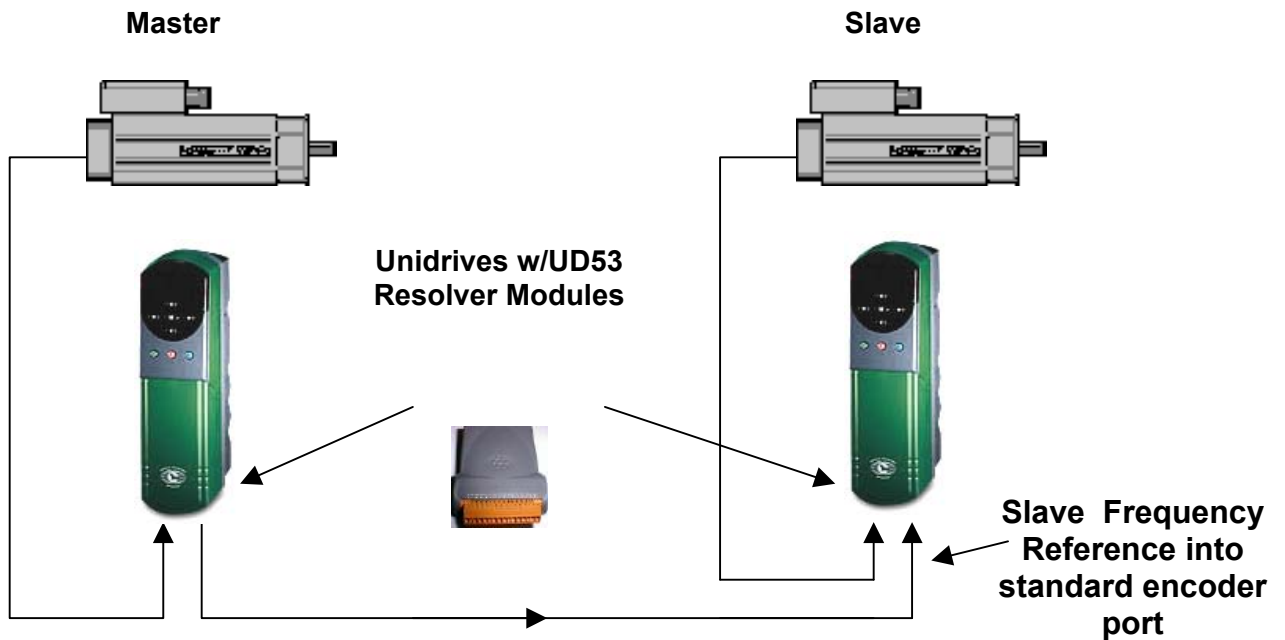
## Initial Parameter Setting for Digital Lock

Parameter #	Value	Comment
2.02	0	Disable Accel Ramps
2.04	1	Fast Ramps- typically requires DB*
3.20	1	Directs Position Trim into Hard Reference via #3.19
13.08	Typically 1 for rigid lock	Digital Lock w/ Feed forward ( see #13.08 for details )
13.07	1.000	Slave Ratio to Master ( max 4.000)
13.09	0.1	Position Loop Gain
13.10	150	Position Trim Limit

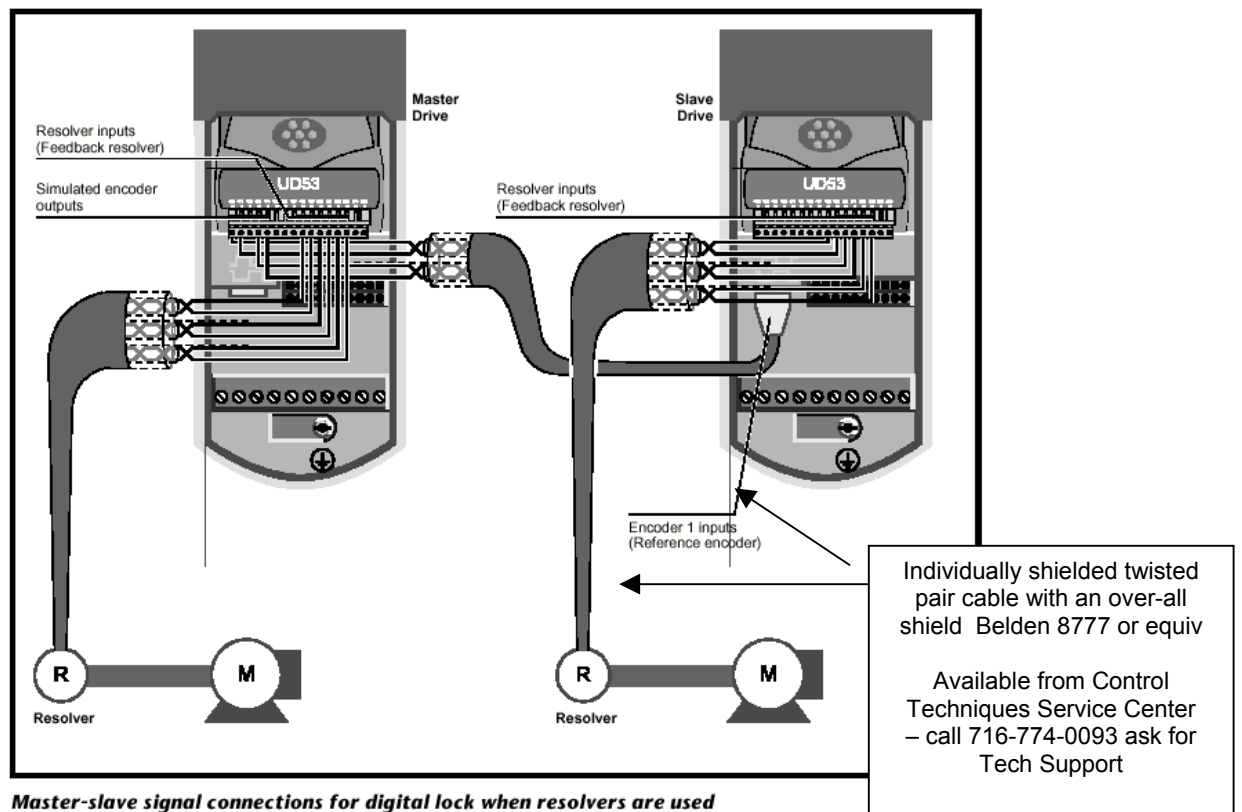
- DB- dynamic braking resistor

# Undrive Digital Lock

## Motors w/Resolver F/B



### Master Frequency Reference using simulated output



## Additional Information on Ratio Adjustment

For Inc/Dec Control of Ratio- click on link below: see Example 2

[www.emersonct.com/pdProducts/downloads/appNotesPDF/ctan114.pdf](http://www.emersonct.com/pdProducts/downloads/appNotesPDF/ctan114.pdf)

For Analog Control of Ratio- click on link below:

[www.emersonct.com/pdProducts/downloads/appNotesPDF/ctan115.pdf](http://www.emersonct.com/pdProducts/downloads/appNotesPDF/ctan115.pdf)



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